# **Omron FINS**



# Description

FINS is an Omron protocol which can be used by a PLC program to transfer data and perform other services with a remote PLC connected on an Ethernet Network.

The FINS protocol can be used by remote devices such as FieldServer to transfer data and perform other services.

The protocol uses the Ethernet protocol called UDP to carry the FINS messages back and forth. The UDP protocol is not connection based and reliability is achieved by using confirmation messages.

This Ethernet Driver can be used to transfer data to and from the Nodes supporting FINS communications.

By default driver uses Ethernet port 9600. This parameter is configurable.

The Driver can be configured as a Client or a Server.

As a Client: This driver reads and writes data to Server Nodes. Server nodes should be FINS capable and be configured to communicate over FINS.

As a Server: Driver responses to read requests and updated FieldServer Data Arrays with data from client.

#### **Connection Facts**

FieldServer Mode	Nodes	Comments		
Client	126	Omron limit the set of permitted nodes to 126. They are numbered 1 to 126 corresponding to the last byte of the remote node IP address.		
Server	20	The FieldServer can emulate a maximum of 20 Omron FINS servers		

## **Formal Driver Type**

Ethernet, Client or Server

## Compatibility

FieldServer Model	Compatible	FieldServer Model	Compatible
ProtoCessor	Yes	QuickServer FS-QS-10xx	No
ProtoCarrier	Yes	QuickServer FS-QS-12xx	Yes
ProtoNode	Yes	QuickServer FS-QS-20xx	Yes
ProtoAir	Yes	QuickServer FS-QS-22xx	Yes
FS-B35 Series	Yes		

## **Connection Information**

Connection Type: Ethernet

Ethernet Speeds Supported: 10Base-T, 100Base-T

# **PLC Types Supported**

PLC Type	Vendor	Physical Medium	
CS1/CJ1 Series	Omron	FINS	

#### **Devices Tested**

Device	Tested (Factory, Site)		
CJ1 Omron PLC	Factory		

# **Communication Functions**

#### Supported FINS Command Set

PLC Type	Memory Type	Command Name	Description	Device Data Type	Format
	I/O Memory	MEMORY AREA READ	Read the contents of consecutive I/O memory area words.	CIO, WR, HR,	Word
	I/O Memory	MEMORY AREA WRITE Writes the contents of consecutive I/O memory area words.		AR, DM, EM	vvord
Operating Mode		RUN Changes the CPU Unit's operating mode to RUN or MONITOR.		-	-
	Changes	STOP	Changes the CPU Unit's operating mode to PROGRAM.		
CS1/CJ1 Series	Time Data Access	CLOCK READ	Reads the present year, month, date, minute, second, and day of the week.		
	Time Data Access	CLOCK WRITE	Changes the present year, month, date, minute, second, or day of the week.	-	-
	Status Reading	CPU UNIT STATUS READ	Reads CPU status, operating mode, other error messages and any text message.	-	-
		CYCLE TIME READ	Reads the CPU average, maximum and minimum cycle time.		

#### **PLC Status to Execute Commands**

PLC Type	Memory Type	Command Name	Run Mode	Monitor Mode	Program Mode	Access Right	UM Read Protection	DIP UM Protection
	1/O Momony	MEMORY AREA READ	OK	OK	OK	OK	OK	OK
	I/O Memory	MEMORY AREA WRITE	OK	OK	OK	OK	OK	OK
	Operating Mode	RUN	OK	OK	OK	Disabled	OK	OK
CS1/CJ1	Changes	STOP	OK	OK	OK	Disabled	OK	OK
Series		CLOCK READ	OK	OK	OK	OK	OK	OK
001100	Time Data Access	CLOCK WRITE	OK	OK	OK	Disabled	OK	OK
Status Reading	CPU UNIT STATUS READ	OK	OK	OK	OK	OK	ОК	
		CYCLE TIME READ	OK	OK	Disabled	OK	OK	OK

Access Right at Other Device: The Access right at other device column tells whether the CPU Unit can or cannot receive a command when another device has the access right to the CPU Unit.

**UM Read Protection:** The UM read protection column tells whether the CPU Unit can or cannot receive the command when UM (user memory) is protected from a Peripheral Device.

**DIP Switch UM Protection:** The DIP switch UM protection column tells whether the CPU Unit can or cannot receive a command when UM is write-protected by turning ON pin 1 of the DIP switch on the CPU Unit's front panel.

#### Unsupported FINS commands

Memory Type	Commands	Description		
	PARAMETER AREA READ			
Parameter Area	PARAMETER AREA WRITE	Read, Write and Clear of Parameters like PLC Setup Area, CPU Bus Unit Setup Area etc.		
	PARAMETER AREA FILL (CLEAR)			
	PROGRAM AREA READ			
Program Area	PROGRAM AREA WRITE	Read, Write and Clear memory for particular Program in PLC.		
	PROGRAM AREA CLEAR			
Machine Configuration Area	CPU UNIT DATA READ	Reads CPU information (Model, Bus unit configuration etc.).		
Machine Configuration Area	CONNECTION DATA READ	Reads CP O Information (Nodel, Bus unit configuration etc.).		
Message Display Area	MESSAGE READ/CLEAR	Reads and Clears messages.		
	ACCESS RIGHT ACQUIRE			
Access Rights Area	ACCESS RIGHT FORCED ACQUIRE	Acquiring and releasing Access right.		
	ACCESS RIGHT RELEASE			
	ERROR CLEAR			
Error Log Area	ERROR LOG READ	Reads and Clear error messages or error log.		
	ERROR LOG POINTER CLEAR			
	FILE NAME READ			
	SINGLE FILE READ			
	SINGLE FILE WRITE			
	FILE MEMORY FORMAT			
	FILE DELETE			
File Memory Area	FILE COPY	File Operations.		
	FILE NAME CHANGE			
	MEMORY AREA-FILE TRANSFER			
	PARAMETER AREA-FILE TRANSFER			
	PROGRAM AREA-FILE TRANSFER	]		
	CREATE/DELETE DIRECTORY			
	FORCED SET/RESET	Foracfully acto reacto hite		
Debugging Area	FORCED SET/RESET CANCEL	Forcefully sets-resets bits.		

Note: FieldServer is a data transfer device, and as such, programming messages are not required.

### **Unsupported Devices or Protocol Options**

Device / Option	Details			
CV Series	CV series PLC's or Ethernet Units (Cannot poll the Ethernet unit itself).			
Socket Services	This is an Omron protocol option that can be used to transfer data between Omron / other device. The Socket Services protocol is different from the FINS protocol and is not supported.			